# **Computation the bow shock at M=4 with a 5th -order WENO scheme**

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## **Spatial discretization: WENO-5**

 Weighted average of interpolated values from all candidate stencils



Shu, 2000, NASA/CR-97-206253 Henric et. al. 2005, *JCP* Bogers et. al. 2008, *JCP*

WENO-5

## **Implicit time integration**

▶ Semi-discretized form

$$
\frac{\partial Q}{\partial t} = R(Q)
$$

- $\triangleright$  Implicit time integration
	- **Significantly relaxed stability constraints**
	- Large time steps (limited by physical considerations), reduce the required CPU time
	- Main difficulty solution of the resulting nonlinear system of equations

## **Implicit time integration - 1**

 $\triangleright$  Implicit1<sup>st</sup> order backward Euler

$$
\frac{Q^{n+1} - Q^n}{\Delta t} = R(Q^{n+1})
$$

Nonlinear implicit equations

$$
F(Q^{n+1}) = \frac{1}{\Delta t} Q^{n+1} - R(Q^{n+1}) - \frac{Q^n}{\Delta t} = 0
$$

## **Implicit time integration - 2**

S-stage, implicit Runge-Kutta schemes

$$
Y_{i} = Q^{n} + \Delta t \sum_{j=1}^{i} a_{ij} R(t_{n} + c_{j} \Delta t, Y_{j}) \qquad i = 1, 2, ..., s
$$

$$
Q^{n+1} = Q^n + \Delta t \sum_{i=1}^{S} b_i R(t_n + c_i \Delta t, Y_i)
$$

i-stage and stage and stage

$$
F(Y_i) = \frac{1}{\Delta t} Y_i - a_{ii} R(t_n + c_i \Delta t, Y_i) - \left[ \frac{Q^n}{\Delta t} + \sum_{j=1}^{i-1} a_{ij} R(t_n + c_j \Delta t, Y_j) \right]
$$
  
= 0

## **Solution of implicit equations**

- General equations  $F(Y_i) = \alpha Y_i + \beta R(Y_i) - b = 0$
- $\triangleright$  Newton iteration  $Y^{k+1} = Y^k + \delta Y^k$

$$
\frac{\partial F}{\partial Y} \delta Y^k = F(Y_i^k)
$$

Convergence test

$$
||F(Y_i^{k+1})||_2 < \varepsilon_{atol}
$$
  

$$
||F(Y_i^{k+1})||_2 < \varepsilon_{rtol} ||F(Y_i^k)||_2
$$
  

$$
||\delta Y^{k+1}||_2 < \varepsilon_{stol}
$$

## **Solution of implicit equations**

 $\triangleright$  LU-SGS – linearization w.r.t. Q<sup>n</sup>

 $AD<sup>2</sup>$ 

Jameson and Yoon, 1987, *AIAAJ* Yoon and Jameson, 1988, *AIAAJ*

$$
\alpha + \beta \frac{\partial h}{\partial q} \delta q^n = b
$$
  
\n
$$
L = \alpha I + \beta (D_x A^+ - A^- + \cdots)
$$
  
\n
$$
LD^{-1} U \delta q^n = b
$$
  
\n
$$
D = \alpha I + \beta (A^+ - A^- + \cdots)
$$
  
\n
$$
U = \alpha I + \beta (D_x^+ A^- + A^+ \cdots)
$$

## **Dispersion and dissipation errors**

- A-stable is NOT sufficient
	- Dispersion and dissipation errors
	- Oscillations of intermediate solutions
	- Numerical instability, increased CPU time

Model equation 
$$
\frac{dQ}{dt} = \mu + i\lambda
$$
  
Amplification  
Numerical  
Amplification  
Exact  
Error 
$$
G = \frac{Q^{n+1}}{Q^n}
$$
  
Function  

$$
G_{exact} = e^{(\mu + i\lambda)\Delta t}
$$
  
Error 
$$
E = \frac{G}{G_{exact}}
$$

### **Dispersion and dissipation errors**



### **Dispersion and dissipation errors**



Du & Ekaterinaris 2016 4<sup>th</sup> order, not A-stable

## **Low-dispersion low-dissipation IMRK**

Du & Ekaterinaris (under review), 2016 4<sup>th</sup> order, not A-stable



#### ▶ Computational grids



#### Mach number contours





#### $\triangleright$  Total temperature



 $\triangleright$  Total pressure – symmetry line, y=0



 $\triangleright$  Total temperature – symmetry line, y=0



### **Convergence histories**

LU-SGS, CFL=20, continuity equation



## **LU-SGS vs IMRK4**

▶ Convergence histories, continuity equation



## **LU-SGS vs IMRK4**

Total pressure



## **LU-SGS vs IMRK4**

#### $\triangleright$  Total temperature



### **Summary**

- The classical 5<sup>th</sup> order WENO scheme was applied for the computation of a bow shock at  $M = 4$ .
- $\triangleright$  Implicit marching was used for fast convergence to the steady state
- $\triangleright$  The numerical predictions for all meshes were in fair agreement
- A small amplitude jump of total temperature at the shock was found for all meshes
- $\triangleright$  A the total temperature before and after the shock remained almost constant for the fine mesh

A small increase in total temperature was found with coarser meshes