# Computation the bow shock at M=4 with a 5<sup>th</sup>-order WENO scheme

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## **Spatial discretization: WENO-5**

Weighted average of interpolated values from all candidate stencils



Shu, 2000, NASA/CR-97-206253 Henric et. al. 2005, *JCP* Bogers et. al. 2008, *JCP*  WENO-5

## Implicit time integration

Semi-discretized form

$$\frac{\partial Q}{\partial t} = R(Q)$$

- Implicit time integration
  - Significantly relaxed stability constraints
  - Large time steps (limited by physical considerations), reduce the required CPU time
  - Main difficulty solution of the resulting nonlinear system of equations

## Implicit time integration - 1

Implicit1<sup>st</sup> order backward Euler

$$\frac{Q^{n+1} - Q^n}{\Delta t} = R(Q^{n+1})$$

Nonlinear implicit equations

$$F(Q^{n+1}) = \frac{1}{\Delta t}Q^{n+1} - R(Q^{n+1}) - \frac{Q^n}{\Delta t} = 0$$

## Implicit time integration - 2

S-stage, implicit Runge-Kutta schemes

$$Y_i = Q^n + \Delta t \sum_{j=1}^{l} a_{ij} R(t_n + c_j \Delta t, Y_j)$$
  $i = 1, 2, ..., s$ 

$$Q^{n+1} = Q^n + \Delta t \sum_{i=1}^{s} b_i R(t_n + c_i \Delta t, Y_i)$$

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$$F(Y_i) = \frac{1}{\Delta t} Y_i - a_{ii} R(t_n + c_i \Delta t, Y_i) - \left[\frac{Q^n}{\Delta t} + \sum_{j=1}^{i-1} a_{ij} R(t_n + c_j \Delta t, Y_j)\right]$$

## Solution of implicit equations

- > General equations  $F(Y_i) = \alpha Y_i + \beta R(Y_i) b = 0$
- > Newton iteration  $Y^{k+1} = Y^k + \delta Y^k$

$$\frac{\partial F}{\partial Y}\delta Y^k = F(Y_i^k)$$

Convergence test

$$\begin{aligned} \left\|F(Y_{i}^{k+1})\right\|_{2} < \varepsilon_{atol} \\ \left\|F(Y_{i}^{k+1})\right\|_{2} < \varepsilon_{rtol} \left\|F(Y_{i}^{k})\right\|_{2} \\ \left\|\delta Y^{k+1}\right\|_{2} < \varepsilon_{stol} \end{aligned}$$

## Solution of implicit equations

LU-SGS – linearization w.r.t. Q<sup>n</sup>

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Jameson and Yoon, 1987, AIAAJ Yoon and Jameson, 1988, AIAAJ

$$\alpha + \beta \frac{\partial R}{\partial q} \delta q^{n} = b$$

$$L = \alpha I + \beta (D_{x}^{-}A^{+} - A^{-} + \cdots)$$

$$LD^{-1}U\delta q^{n} = b \qquad D = \alpha I + \beta (A^{+} - A^{-} + \cdots)$$

$$U = \alpha I + \beta (D_{x}^{+}A^{-} + A^{+} \cdots)$$

## **Dispersion and dissipation errors**

- A-stable is NOT sufficient
  - Dispersion and dissipation errors
  - Oscillations of intermediate solutions
  - Numerical instability, increased CPU time

Model equation 
$$\frac{dQ}{dt} = \overset{\downarrow}{\mu} + i\lambda$$
Amplification
Numerical
$$G = \frac{Q^{n+1}}{Q^n}$$
Amplification
Exact
$$G_{exact} = e^{(\mu+i\lambda)\Delta t}$$
Error
$$E = \frac{G}{G_{exact}}$$

### **Dispersion and dissipation errors**



### **Dispersion and dissipation errors**



Du & Ekaterinaris 2016 4<sup>th</sup> order, not A-stable

## Low-dispersion low-dissipation IMRK

Du & Ekaterinaris (under review), 2016 4<sup>th</sup> order, not A-stable

0.135497354012	0.135497354012		
0.510315342452	0.388552068308	0.121763274144	
0.870923224178	0.271286420495	0.470560027861	0.129076775822
	0.316195414959	0.383754607157	0.300049977884

#### Computational grids



#### Mach number contours



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#### > Total temperature



Total pressure – symmetry line, y=0



> Total temperature – symmetry line, y=0



### **Convergence histories**

> LU-SGS, CFL=20, continuity equation



## LU-SGS vs IMRK4

> Convergence histories, continuity equation



## LU-SGS vs IMRK4

Total pressure



## LU-SGS vs IMRK4

#### > Total temperature



### Summary

- The classical  $5^{\text{th}}$  order WENO scheme was applied for the computation of a bow shock at M = 4.
- > Implicit marching was used for fast convergence to the steady state
- > The numerical predictions for all meshes were in fair agreement
- A small amplitude jump of total temperature at the shock was found for all meshes
- A the total temperature before and after the shock remained almost constant for the fine mesh

> A small increase in total temperature was found with coarser meshes